

# Meta-classifiers for Exploiting Feature Dependencies in Automatic Target Recognition

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# Automatic Target Recognition (ATR)

- Exploit imagery from diverse sensed sources for automatic target identification<sup>1</sup>
- Variety of **sensors**: synthetic aperture radar (SAR), inverse SAR (ISAR), forward looking infra-red (FLIR), hyperspectral
- Diverse scenarios: air-to-ground, air-to-air, surface-to-surface

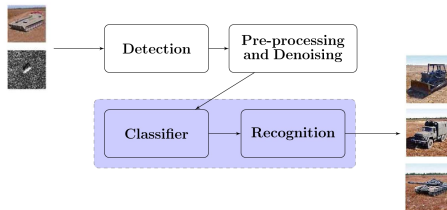


**Figure:** Sample targets and their SAR images. Courtesy: Gomes et al.

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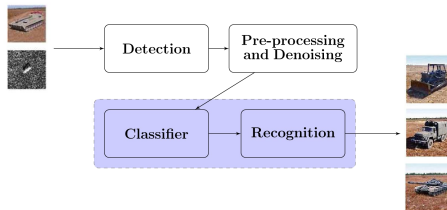
<sup>1</sup>Bhanu et al., IEEE AES Systems Magazine, 1993

# ATR system description



**Figure:** Schematic of ATR framework. The classification and recognition stages assign an input image/ feature to one of many target classes.

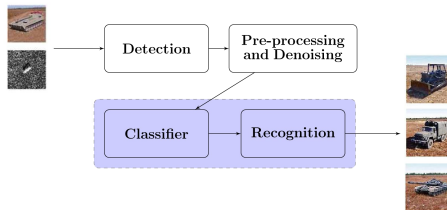
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- **Detection** and **discrimination**: Identification of target signatures in the presence of clutter

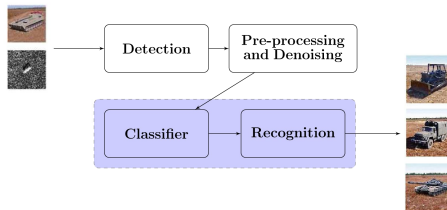
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- **Denoising**: Pre-processing (e.g. removing speckle in SAR imagery)

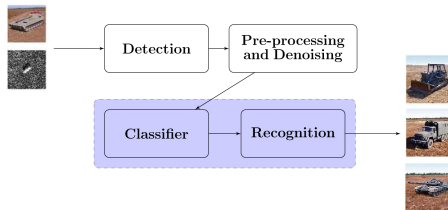
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- **Detection** and **discrimination**: Identification of target signatures in the presence of clutter
- **Denoising**: Pre-processing (e.g. removing speckle in SAR imagery)
- **Classification**: Separation of targets into different classes
- **Recognition**: Distinguishing between sub-classes within a target class; harder problem than classification

# Target classification

- Rich family of algorithmic tools developed over two decades
- Two-stage framework

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<sup>2</sup>Olson et al., IEEE Trans. Image Process., 1997

<sup>3</sup>Casasent et al., Neural Networks, 2005

<sup>4</sup>Gomes et al., IEEE Radar Conf., 2008

<sup>5</sup>Bhatnagar et al., IEEE ICASSP, 1998

<sup>6</sup>Grenander et al., IEEE Trans. PAMI, 1998



# Target classification

- Rich family of algorithmic tools developed over two decades
- Two-stage framework
- Feature extraction from sensed imagery
  - Geometric feature-point descriptors<sup>2</sup>
  - Transform domain coefficients - wavelets<sup>3,4</sup>
  - Eigen-templates<sup>5</sup>
  - Estimation-theoretic templates<sup>6</sup>

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# Target classification

- **Decision engine** which performs class assignment
  - Linear and quadratic discriminant analysis
  - Neural networks<sup>7</sup>
  - Support vector machines (SVM)<sup>8</sup>
  - Hierarchical SVM<sup>9</sup>

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<sup>7</sup> Daniell et al., Optical Engineering, 1992

<sup>8</sup> Zhao et al., IEEE Trans. Aerosp. Electron. Syst., 2001

<sup>9</sup> Casasent et al., Neural Networks, 2005

# Recent research trends

- Search for 'best possible' features from a classification standpoint
- Limited understanding of inter-relationships among different sets of features

# Recent research trends

- Search for ‘best possible’ features from a classification standpoint
- Limited understanding of inter-relationships among different sets of features
- No single **optimal** feature set-decision engine combination
- Exploit **complementary yet correlated** information offered by different sets of classifiers
  - Classifier fusion

# Classifier fusion

- Same set of features with different decision engines; (mostly) educated heuristic schemes
- Combination of outputs from four decision engines using FLIR data<sup>10</sup>
- Product of individual classification probabilities<sup>11</sup>
- Voting strategy<sup>12</sup>
- Boosting<sup>13</sup>

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<sup>10</sup> Rizvi et al., Applied Imagery Pattern Recognition Workshop, 2003

<sup>11</sup> Paul et al., IEEE ICASSP, 2003

<sup>12</sup> Gomes et al., IEEE Radar Conf., 2008

<sup>13</sup> Sun et al., IEEE Trans. Aerosp. Electron. Syst., 2007

<sup>14</sup> Nasrabadi, IEEE Int. Conf. Image Process., 2008

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- Related research problem: multi-sensor ATR<sup>14</sup>

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# Contribution of our work

- **Meta-classification:** Principled strategy to combine complementary benefits<sup>15</sup>

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- **Meta-classification:** Principled strategy to combine complementary benefits<sup>15</sup>
- **Meta-classifier:** Combines classifier decisions from individual classifiers to improve overall classification performance
- Two-stage approach:
  - ① Obtain different feature sets via **multiple projections** (to suitable basis)
  - ② Combine “soft” outputs from individual classifiers into composite **meta-feature vector** for classification

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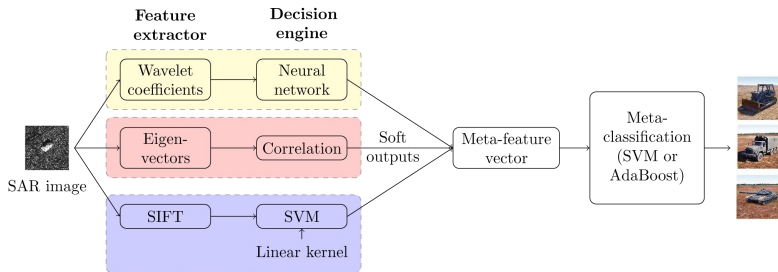
# Contribution of our work

- **Meta-classification:** Principled strategy to combine complementary benefits<sup>15</sup>
- **Meta-classifier:** Combines classifier decisions from individual classifiers to improve overall classification performance
- Two-stage approach:
  - ① Obtain different feature sets via **multiple projections** (to suitable basis)
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- Two intuitively-motivated schemes proposed for SAR imagery:
  - Meta-classification using **SVMs**
  - Meta-classification using **boosting**

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# Meta-classification framework



- Complementary merits of different sets of features exploited
- Meta-classification: Creates common ground for combination of diverse types of features

# Different feature extractors

- 1 Wavelet features + neural network<sup>16</sup>
  - Transform domain features (in  $\mathbb{R}^{256}$ )
  - LL sub-band coefficients from two-level decomposition using reverse biorthogonal wavelets
  - Multilayer perceptron neural network

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<sup>17</sup> Bhatnagar et al., IEEE ICASSP, 1998

<sup>18</sup> Grauman et al., Int. Conf. Comp. Vision, 2005

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- 2 Eigen-templates + correlation<sup>17</sup>
  - Spatial domain features (in  $\mathbb{R}^{4096}$ )
  - Training class template: eigen-vector corresponding to largest singular value of training data matrix
  - Decision engine: correlation score

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  - Training class template: eigen-vector corresponding to largest singular value of training data matrix
  - Decision engine: correlation score
- 3 Scale invariant feature transform (SIFT) + SVM
  - Computer vision-based features (in  $\mathbb{R}^{128}$ )
  - SIFT: robustness to change in image scale, illumination, local geometric transformations and noise
  - SVM decision engine<sup>18</sup>

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# Support Vector Machine<sup>19</sup>

- Decision function of binary SVM classifier:

$$f(\mathbf{x}) = \sum_{i=1}^N \alpha_i y_i K(\mathbf{s}_i, \mathbf{x}) + b,$$

where  $\mathbf{s}_i$  are support vectors,  $N$  is the number of support vectors

- Kernel  $K : \mathbb{R}^n \times \mathbb{R}^n \mapsto \mathbb{R}$  maps feature space to higher-dimensional space where separating hyperplane may be more easily determined
- Binary classification decision for  $\mathbf{x}$  depending on whether  $f(\mathbf{x}) > 0$  or otherwise
- Multi-class classifiers: one-versus-all approach

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<sup>19</sup>Vapnik, The nature of statistical learning theory, 1995

# Boosting<sup>20</sup>

- Boost the performance of weak learners into a classification algorithm with arbitrarily accurate performance
- Maintain a distribution of weights over the training set
- Weights on incorrectly classified examples are increased iteratively
- Slow learners are penalized for harder examples

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## Algorithm 1 AdaBoost learning algorithm

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1: Input data  $(x_i, y_i)$ ,  $i = 1, 2, \dots, N$ , where  $x_i \in S$ ,  $y_i \in \{-1, +1\}$

2: Initialize  $D_1(i) = \frac{1}{N}$ ,  $i = 1, 2, \dots, N$

3: For  $t = 1, 2, \dots, T$ :

- Train weak learner using distribution  $D_t$
- Determine weak hypothesis  $f_t : S \mapsto \{-1, +1\}$  with error  $\epsilon_t$
- Choose  $\beta_t = \frac{1}{2} \ln \left( \frac{1-\epsilon_t}{\epsilon_t} \right)$
- $D_{t+1}(i) = \frac{D_t(i) \exp(-\beta_t y_i f_t(x_i))}{Z_t}$ , where  $Z_t$  is a normalization factor

4: Output soft decision  $F(x) = \sum_{t=1}^T \beta_t f_t(x)$ .

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<sup>20</sup> Freund et al., Journal of Japanese Society for Artificial Intelligence, 1999

# Image pre-processing

- SAR imagery: low spatial resolution and contrast, clutter, noise
- **Speckle noise**: Interference between radar waves reflected off target; signal-dependent and multiplicative

$$y[\mathbf{m}] = x[\mathbf{m}] + \sqrt{x[\mathbf{m}]} n[\mathbf{m}]$$

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- Speckle denoising: important inverse problem<sup>21</sup>
- Denoising using anisotropic diffusion<sup>22</sup>
  - Better mean preservation
  - Variance reduction
  - Edge localization

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- Speckle denoising: important inverse problem<sup>21</sup>
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  - Better mean preservation
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  - Edge localization
- Registration of image templates - frame centering
- Energy normalization

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<sup>22</sup>Yu et al., IEEE Trans. Image Process., 2002

# Experiments

- Moving and Stationary Target Acquisition and Recognition (MSTAR) database for SAR images
- Five target classes
  - 1 T-72 tanks
  - 2 BMP-2 infantry fighting vehicles
  - 3 BTR-70 armored personnel carriers
  - 4 ZIL131 trucks
  - 5 D7 tractors
- SLICY confusers to test rejection performance

Target class	Serial number	# Training images	# Test images
BMP-2	SN_C21	233	196
	SN_9563	233	195
	SN_9566	232	196
BTR-70	SN_C71	233	196
T-72	SN_132	232	196
	SN_812	231	195
	SN_S7	228	191
ZIL131	-	299	274
D7	-	299	274

Table: Target classes in the experiment.

# Results: Classification

Table: Confusion matrix for **wavelet features + neural network** classifier.

	BMP-2	BTR-70	T-72	ZIL131	D7	Other
BMP-2	<b>0.80</b>	0.06	0.09	0.01	0.04	0
BTR-70	0.03	<b>0.93</b>	0.02	0	0.02	0
T-72	0.08	0	<b>0.77</b>	0.10	0.04	0.01
ZIL131	0.08	0	0.05	<b>0.84</b>	0.03	0
D7	0	0.03	0.06	0.05	<b>0.86</b>	0
Confuser	0	0	0.01	0	0	<b>0.99</b>

(a)

Table: Confusion matrix for **eigen-template matching** classifier.

	BMP-2	BTR-70	T-72	ZIL131	D7	Other
BMP-2	<b>0.76</b>	0.09	0.05	0.03	0.05	0.02
BTR-70	0.04	<b>0.88</b>	0.05	0	0.03	0
T-72	0.06	0.06	<b>0.73</b>	0.10	0.04	0.01
ZIL131	0.02	0.04	0.07	<b>0.79</b>	0.08	0
D7	0	0.03	0.06	0.04	<b>0.87</b>	0
Confuser	0.01	0	0	0	0	<b>0.99</b>

(b)

Table: Confusion matrix for **SIFT features + linear SVM** classifier.

	BMP-2	BTR-70	T-72	ZIL131	D7	Other
BMP-2	<b>0.85</b>	0.07	0.03	0	0.03	0.02
BTR-70	0.02	<b>0.91</b>	0.05	0	0.02	0
T-72	0.03	0.04	<b>0.82</b>	0.06	0.04	0.01
ZIL131	0	0.04	0.03	<b>0.86</b>	0.07	0
D7	0	0	0.06	0.05	<b>0.89</b>	0
Confuser	0.01	0	0.02	0	0	<b>0.97</b>

(c)

# Results: Classification

Table: Confusion matrix for SVM meta-classifier.

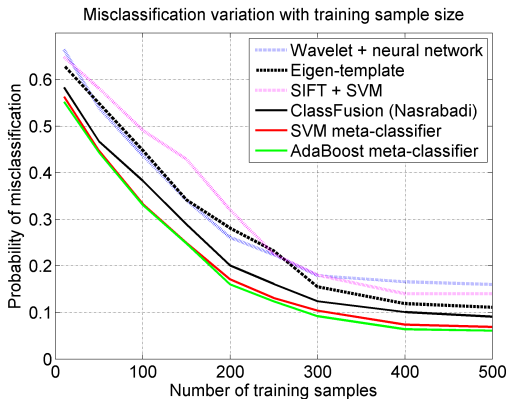
	BMP-2	BTR-70	T-72	ZIL131	D7	Other
BMP-2	<b>0.91</b>	0.03	0.02	0.02	0.03	0
BTR-70	0.01	<b>0.94</b>	0.02	0.01	0.02	0
T-72	0.03	0.02	<b>0.89</b>	0.03	0.03	0
ZIL131	0.01	0.04	0.03	<b>0.89</b>	0.03	0
D7	0	0.01	0.05	0.04	<b>0.90</b>	0
Confuser	0	0	0	0	0	<b>1.00</b>

Table: Confusion matrix for AdaBoost meta-classifier.

	BMP-2	BTR-70	T-72	ZIL131	D7	Other
BMP-2	<b>0.93</b>	0.02	0.03	0.01	0.01	0
BTR-70	0.02	<b>0.95</b>	0.02	0	0.01	0
T-72	0.04	0.02	<b>0.89</b>	0.04	0.02	0
ZIL131	0.01	0.03	0.02	<b>0.90</b>	0.04	0
D7	0	0.03	0.03	0.03	<b>0.91</b>	0
Confuser	0	0	0	0	0	<b>1.00</b>

# Experiment: Performance as function of training size

- Practical concern for ATR: limited training resources
- Binary classification problem: T-72 and BMP-2 classes
- Probability of misclassification  $\rightarrow$  average of false-alarm and miss.



# Conclusions

- Virtues of different feature extractors and decision engines combined in a principled manner
- Two meta-classification schemes proposed, based on SVM and AdaBoost
- Test on benchmark SAR datasets show improvements in classification performance
- Robustness in limited training paradigm; superior asymptotic performance

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- Test on benchmark SAR datasets show improvements in classification performance
- Robustness in limited training paradigm; superior asymptotic performance
- **Extension of current work:** graphical-model based classification framework to exploit feature dependencies<sup>23</sup>

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